

Generalising Calabi–Yau for flux backgrounds

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What is the geometry of a generic $\mathcal{N} = 2$ flux background?

- No fluxes \rightarrow complex/symplectic geometry.
- NS-NS fluxes \rightarrow generalised complex geometry.
- All fluxes \rightarrow exceptional generalised geometry.

- 1 Introduction
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- 3 H and V structures
- 4 Marginal deformations for AdS/CFT

Supersymmetric backgrounds

Backgrounds with no fluxes

$$\nabla\epsilon = 0 \quad \implies \quad \text{special holonomy}$$

e.g. type II on Calabi–Yau

$$\omega_{mn} \sim \epsilon^\dagger \gamma_{mn} \epsilon, \quad \Omega_{mnp} \sim \epsilon^T \gamma_{mnp} \epsilon$$

Integrable SU(3) structure if

$$d\Omega = d\omega = 0 \quad \Leftrightarrow \quad \nabla\epsilon = 0$$

Calabi–Yau \Leftrightarrow integrable SU(3) structure $\Leftrightarrow \mathcal{N} = 2$ in 4d

Supersymmetric backgrounds

Backgrounds with fluxes

With fluxes, Levi-Civita \rightarrow supergravity connection, e.g. type II

$$(\nabla_m \mp \frac{1}{8} H_{mnp} \gamma^{np}) \epsilon^\pm + \frac{1}{16} e^\phi \sum_i \#_i \gamma_m \epsilon^\mp = 0$$

$$\gamma^m (\nabla_m \mp \frac{1}{24} H_{mnp} \gamma^{np} - \partial_m \phi) \epsilon^\pm = 0$$

Any underlying geometry?

- Special holonomy?
- Analogues of ω and Ω ? Integrability?
- Deformations and moduli spaces?

Supersymmetric backgrounds

One approach: G -structures

Killing spinors **stabilised** by

$$G \subset \mathrm{SO}(6) \subset \mathrm{GL}(6)$$

and define a **G -structure**, but not integrable

$$d\Omega \sim \text{flux}, \quad d\omega \sim \text{flux}$$

Good for classification and new solutions, but

- Global issues: “type changing”.
- Moduli are difficult, $d\delta\Omega, d\delta\omega \neq 0$.

[Gauntlett, Martelli, Waldram; Gauntlett, Pakis; Martelli, Sparks; Lüst, Tsimpis;...]

Supersymmetric backgrounds

Generalised Calabi–Yau

Killing spinors **stabilised** by

$$SU(3) \times SU(3) \subset SO(6) \times SO(6) \subset O(6,6) \times \mathbb{R}^+$$

and define a G -structure, **integrable** for NS-NS backgrounds

$$d\Phi^+ = 0, \quad d\Phi^- = 0$$

Each $\Phi^\pm \in \Gamma(\wedge^\pm T^*M)$ defines **$SU(3,3)$ structure**.

$$\Phi^+ = e^{-\phi} e^{-B-i\omega}, \quad \Phi^- = e^{-\phi} e^{-B}(\Omega_1 + \Omega_3 + \Omega_5)$$

[Hitchin; Gualtieri; Graña, Minasian, Petrini, Tomasiello]

Supersymmetric backgrounds

Generic $\mathcal{N} = 2$ backgrounds

Keep all fluxes, warped compactification

$$ds^2 = e^{2\Delta} ds^2(\mathbb{R}^{3,1}) + ds^2(M)$$

where M is 6d for type II and 7d for M-theory.

In sugra, spinors transform as $\mathbf{8}$ of $SU(8)$: pair of Killing spinors **stabilised** by

$$SU(6) \subset SU(8) \subset E_{7(7)} \times \mathbb{R}^+$$

and define a **generalised $SU(6)$ structure**.

What is the geometry of a generic $\mathcal{N} = 2$ flux background?

- Generalisations of ω and Ω ? Define generalised $SU(6)$ structure.
- Integrability?
- Moduli space?

Structures in generalised geometry

[Graña, Louis, Sim, Waldram; Graña, Orsi; Graña, Triendl]

Outline

- 1 Introduction
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- 3 H and V structures
- 4 Marginal deformations for AdS/CFT

Generalised geometry

$E_{d(d)} \times \mathbb{R}^+$ generalised geometry

Unifies all symmetries, restricted to M_{d-1} in type II or M_d in M-theory

What do we need?

- **Generalised tangent bundle** whose sections parametrise the symmetries.
- **Generalised Lie derivative** by which the symmetries act.

Focus on type II

- Fields $\{g, \phi, B, \tilde{B}, C^\pm, \Delta\}$ on M_{d-1} .

[Coimbra, Strickland-Constable, Waldram; Hull; Pacheco, Waldram; Berman, Perry;...]
cf. [Hitchin; Gualtieri; Baraglia; Cremmer, Julia; de Wit, Nicolai; Siegel; Hohm, Kwak, Zweibach; Jeon, Lee, Park;...]

Generalised geometry

Generalised tangent bundle

$$E \simeq TM \oplus T^*M \oplus \wedge^5 T^*M \oplus \wedge^\pm T^*M \oplus (T^*M \otimes \wedge^6 T^*M)$$

$$V^M = (v^m, \lambda_m, \tilde{\lambda}_{m_1 \dots m_5}, \lambda^\pm, \tau_{m, n_1 \dots n_7})$$

E encodes diffeomorphisms and gauge transformations, e.g.

$$\delta B = \mathcal{L}_v B + d\lambda, \quad \delta C^\pm = \mathcal{L}_v C^\pm + d\lambda^\pm$$

Generalised Lie derivative

$$L_v = \text{diffeos} + \text{gauge} \quad \text{"Leibniz algebroid"}$$

[Hull; Pacheco, Waldram; Coimbra, Strickland-Constable, Waldram]

Adjoint bundle

Tensors transform as $E_{d(d)} \times \mathbb{R}^+$ representations

$$\begin{aligned} \text{ad } \tilde{F} \simeq & \mathbb{R} \oplus (TM \otimes T^*M) \oplus \wedge^2 TM \oplus \wedge^2 T^*M \oplus \wedge^6 TM \oplus \wedge^6 T^*M \\ & \oplus \wedge^\pm TM \oplus \wedge^\pm T^*M \end{aligned}$$

$$R^M_N = (\dots, B_{mn}, \dots, C^\pm)$$

Potentials give isomorphism between E and $TM \oplus T^*M \oplus \dots$

$$V = e^{B+C^\pm} \tilde{V}$$

Generalised geometry

“Supergravity = generalised geometry”

Neatly describes supergravity on M_{d-1}

- Generalised metric G_{MN} equivalent to $\{g, \phi, B, \tilde{B}, C^\pm, \Delta\}$.

Analogue of Levi-Civita connection

- Gen. **torsion-free** connection D , **compatible** with gen. metric: $DG = 0$.

Gen. Ricci tensor gives bosonic action

$$S_B = \int_M |\text{vol}_G| R \quad \Longrightarrow \quad \text{eq. of motion} = \text{gen. Ricci flat}$$

[Coimbra, Strickland-Constable, Waldram]

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Conventional G -structures

G -structure defined by **invariant tensors**.

$$\text{symplectic } \omega : G = \text{Sp}(3; \mathbb{R})$$

$$\text{complex } \Omega : G = \text{SL}(3; \mathbb{C})$$

$$\{\omega, \Omega\} : G = \text{SU}(3)$$

Analogues with **flux**?

Generalised structures

Generalised G -structures, defined by invariant generalised tensors.

$$\text{H structure } J_\alpha : G = \text{SO}^*(12)$$

$$\text{V structure } K : G = \text{E}_{6(2)}$$

$$\text{HV structure } \{J_\alpha, K\} : G = \text{SU}(6)$$

- J_α and K associated with hyper- and vector-multiplets.
- Interpolate between symplectic, complex, product and hyper-Kähler.

[Graña, Louis, Sim, Waldram]

Hypermultiplet structures

H structure: $SO^*(12)$

Weighted tensor in $\mathbf{133}_1$ of $E_{7(7)} \times \mathbb{R}^+$

$$J_\alpha \in \Gamma(\text{ad } \tilde{F} \otimes (\det T^* M)^{1/2})$$

giving highest weight \mathfrak{su}_2 algebra

$$[J_\alpha, J_\beta] = 2\kappa \epsilon_{\alpha\beta\gamma} J_\gamma, \quad \text{tr}(J_\alpha J_\beta) = -\kappa^2 \delta_{\alpha\beta} \in \Gamma(\det T^* M)$$

Constructed from spinor bilinears: $J_\alpha = e^{B+C^\pm+\dots} (\sigma_\alpha^{ij} \epsilon_i \otimes \bar{\epsilon}_j)$

Generalises Ω in IIA and ω in IIB

Vector-multiplet structures

V structure: $E_{6(2)}$

Generalised vector in $\mathbf{56}_1$ of $E_{7(7)} \times \mathbb{R}^+$

$$K \in \Gamma(E) \quad \text{satisfying } q(K) > 0$$

where q is the $E_{7(7)}$ quartic invariant

- $q(K)$ as “Hitchin functional” defines second vector \hat{K} .

Constructed from spinor bilinears: $K = e^{B+C^\pm+\dots}(\epsilon^{ij} \epsilon_i \otimes \epsilon_j^T)$

Generalises ω in IIA and Ω in IIB

Compatibility and SU(6)

HV structure

The structures are **compatible** if

$$J_\alpha \cdot K = 0, \quad \text{tr}(J_\alpha J_\beta) = -2\sqrt{q(K)}\delta_{\alpha\beta}$$

analogues of $\omega \wedge \Omega = 0$ and $\frac{1}{6}\omega^3 = \frac{i}{8}\Omega \wedge \bar{\Omega}$.

Structures intersect on $SO^*(12) \cap E_{6(2)} = SU(6)$.

A compatible pair $\{J_\alpha, K\} \implies$ **SU(6) structure**

Example: CY in IIA

H structure

$$J_+ = \frac{1}{2}\kappa(\Omega - \Omega^\sharp)$$

$$J_3 = \frac{1}{2}\kappa(I - \text{vol}_6 - \text{vol}_6^\sharp)$$

where $\kappa^2 = \text{vol}_6 = \frac{i}{8}\Omega \wedge \bar{\Omega}$ and I is complex structure.

V structure

$$K + i\hat{K} = e^{-i\omega}$$

H structure

$$J_+ = \frac{1}{2}\kappa(e^{-i\omega} - e^{-i\omega^\sharp})$$

$$J_3 = \frac{1}{2}\kappa(\omega + \omega^\sharp - \text{vol}_6 - \text{vol}_6^\sharp)$$

where $\kappa^2 = \text{vol}_6 = \frac{1}{6}\omega^3$.

V structure

$$K + i\hat{K} = \Omega$$

Many examples

Minkowski

- Generalised Calabi–Yau (pure spinors)
- D3-branes on $\text{HK} \times \mathbb{R}^2$ in IIB
- Wrapped M5-branes on $\text{HK} \times \mathbb{R}^3$ in M-theory

AdS

- Sasaki–Einstein in 5d (IIB) and 7d (M-theory)
- Most general AdS_5 solutions in IIB and M-theory

Differential conditions

Spaces of H and V structures admit action of **generalised diffeomorphisms**

$$\mathbf{GDiff} = \text{Diff} \ltimes \text{gauge}$$

and can define moment maps.

$$\text{integrability} \iff \text{vanishing moment map}$$

Integrability for H structures

Consider space of H structures, coordinates $J_\alpha \in \mathcal{A}_H$

- \mathcal{A}_H has **hyper-Kähler** metric, inherited fibrewise from

$$J_\alpha(x) \in W = \frac{E_{7(7)} \times \mathbb{R}^+}{\text{Spin}^*(12)}$$

where W is HK cone over symmetric quaternionic-Kähler (**Wolf**) space.

- \mathcal{A}_H is also a **HK cone**, global $\mathbb{H}^+ = \text{SU}(2) \times \mathbb{R}^+$.

Integrability for H structures

Hyper-Kähler structure on \mathcal{A}_H preserved by diffeos and gauge transformations, parametrised by $V \in \Gamma(E) \simeq \mathfrak{g}\text{diff}$

$$\delta J_\alpha = L_V J_\alpha \in T_J \mathcal{A}_H$$

Moment maps

$$\mu_\alpha(V) = -\frac{1}{2} \epsilon_{\alpha\beta\gamma} \int_M \text{tr}(J_\beta L_V J_\gamma)$$

where $\mu_\alpha: \mathcal{A}_H \rightarrow \mathfrak{g}\text{diff}^*$.

Integrability for H structures

Integrability

$$\mu_\alpha(V) = 0 \quad \text{for all } V \in \Gamma(E)$$

For CY in IIA or IIB, gives $d\Omega = 0$ or $d\omega = 0$.

Moduli space

Structures related by GDif are equivalent, **moduli space** is a **hyper-Kähler quotient**

$$\mathcal{M}_H = \mathcal{A}_H // \text{GDif} = \mu_1^{-1}(0) \cap \mu_2^{-1}(0) \cap \mu_3^{-1}(0) / \text{GDif}$$

HK cone over usual QK moduli space of hypermultiplets.

Integrability for V structures

Consider space of V structures, coordinates $K \in \mathcal{A}_V$

- \mathcal{A}_H has **special-Kähler** metric, inherited fibrewise from

$$K \in P = \frac{E_{7(7)} \times \mathbb{R}^+}{E_{6(2)}}$$

where P is special-Kähler.

Moment maps

Again, $\mathfrak{g}\text{diff}$ acts as $\delta K = L_V K \in T_K \mathcal{A}_V$ and **preserves SK structure**, giving

$$\mu: \mathcal{A}_V \rightarrow \mathfrak{g}\text{diff}^*$$

$$\mu(V) = \frac{1}{2} \int_M s(K, L_V K)$$

where $s(\cdot, \cdot)$ is $E_{7(7)}$ symplectic invariant.

Integrability for V structures

Integrability

$$\mu(V) = 0 \quad \text{for all } V \in \Gamma(E)$$

For CY in IIA or IIB, gives $(d\Omega)_{3,1} = 0$ or $\omega \wedge d\omega = 0$.

Moduli space

Structures related by GDiff are equivalent, **moduli space** is a symplectic quotient

$$\mathcal{M}_V = \mathcal{A}_V // \text{GDiff} = \mu^{-1}(0) / \text{GDiff}$$

SK cone over the usual SK moduli space of vector-multiplets.

Integrability for HV structures

$\mathcal{N} = 2$ backgrounds

H and V structures that are individually integrable are **not sufficient**. Need extra condition that couples them (unlike CY!)

$$\mu_\alpha(V) = \mu(V) = 0 \quad \text{plus} \quad L_K J_\alpha = L_{\hat{K}} J_\alpha = 0$$

For CY, recover $d\omega = d\Omega = 0$.

“Exceptional Calabi–Yau” $\Leftrightarrow \mathcal{N} = 2$ with flux

Why these conditions?

Intrinsic torsion

SUSY equivalent to existence of generalised **torsion-free** connection D that is **compatible** with the structures

$$DJ_\alpha = DK = 0, \quad T(D) = \{0\}$$

Integrability constrains same representations that appear in torsion.

[Coimbra, Strickland-Constable, Waldram]

Gauged $\mathcal{N} = 2$ supergravity

Rewrite 10d theory as $D = 4$, $\mathcal{N} = 2$ but keep **all KK modes**.

- Gauged 4d supergravity with infinite number of hypers and vectors.
- Integrability just $\mathcal{N} = 2$ vacuum conditions.

[Louis, Smyth, Triendl; Hristov, Looyestijin, Vandoren]

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Sasaki–Einstein

$\mathcal{N} = 1$ AdS backgrounds in type IIB with $F_5 \neq 0$

$$ds_{10}^2 = ds^2(\text{AdS}_5) + ds^2(\text{SE}_5), \quad F_5 = dC_4 = 4 \text{vol}_5$$

Cone over SE₅ is **Calabi–Yau**.

- Contact form $\sigma = d\psi + \eta$, dual to **Reeb vector** ξ – nowhere-vanishing Killing vector.

$$\begin{aligned} \iota_\xi \sigma &= 1, & \iota_\xi \omega &= \iota_\xi \Omega = 0, & \omega \wedge \Omega &= 0, \\ d\sigma &= 2\omega, & d\Omega &= 3i\sigma \wedge \Omega, & \mathcal{L}_\xi \Omega &= 3i\Omega \end{aligned}$$

AdS₅ × SE₅ in type IIB

HV structure

$$\left. \begin{array}{l} J_\alpha, \quad G = \text{SU}^*(6) \\ K, \quad G = \text{F}_{4(4)} \end{array} \right\} G = \text{USp}(6)$$

where $K \sim e^{C_4}(\xi + \sigma \wedge \omega)$, $J_+ \sim e^{C_4}(\Omega + \Omega^\sharp)$.

Integrability for AdS

$$\mu_\alpha(V) = \lambda_\alpha \int_M c(K, K, V), \quad L_K K = 0, \quad L_K J_\alpha = \epsilon_{\alpha\beta\gamma} \lambda_\beta J_\gamma$$

where $c(\cdot, \cdot, \cdot)$ is E₆₍₆₎ cubic invariant.

- Implies K is “generalised Killing vector”.

Marginal deformations

“Superpotential” deformations: $\delta J_\alpha = [R, J_\alpha] \neq 0$, $\delta K = 0$

Dual to **marginal deformations** of $\mathcal{N} = 1$ SCFT

- R contains two-form and bivector components
- R generates flux

$$F_3 + iH \propto f\sigma \wedge \bar{\Omega} + \dots, \quad \mathcal{L}_\xi f = 3if$$

where f is **holomorphic** on CY cone.

Marginal deformations

Which deformations can be extended to all orders? Higher-order calculations constrain f – long and difficult! [Aharony, Kol, Yankielowicz]

Moment map: no obstructions unless there are additional symmetries at $f = 0$.

Further quotient by

$$\mathfrak{g} = \{V \in \mathfrak{g}_{\text{diff}} : L_V J_\alpha = L_V K = 0\}$$

Supergravity version of [Green, Komargodski, Seiberg, Tachikawa, Wecht]

Marginal deformations

Example: S^5

Cone over S^5 is \mathbb{C}^3 with coordinates z_i : $\mathcal{L}_\xi z_i = iz_i$

$$f = f^{ijk} z_i z_j z_k$$

$SU(3) \subset \text{GDiff}$ leaves $\{J_\alpha, K\}$ fixed, **obstruction** is $SU(3)$ moment map

$$\gamma_j^i = f^{ikl} \bar{f}_{jkl} - \frac{1}{3} \delta_j^i f^{klm} \bar{f}_{klm} = 0$$

Only $10 - 8 = 2$ complex degrees of freedom in f .

AdS/CFT: $\gamma_j^i = 0$ just one-loop beta-function conditions, 2 **exactly marginal deformations** of $\mathcal{N} = 4$ SYM.

Summary

- Combines symplectic, complex, HK structures.
- Moduli space c.f. hyper-Kähler quotient.
- Reductions of type II and 11d supergravity to 4, 5 and 6 dimensions, Minkowski or AdS.
- AdS/CFT: deformations plus obstructions from symmetries.
 - Also works for 3d $\mathcal{N} = 2$ theories with M-theory duals.

Questions

- $\mathcal{N} = 1$ backgrounds? Heterotic?
- Exponentiate deformations?
- Deformations are part of complex. Underlying DGLA?
- AdS: volume minimisation, calibrations?
- Links to topological string?